# SmartScope<sup>®</sup> TTL Laser

QVI<sup>®</sup> Through-the-Lens Lasers offer a non-contact method for measuring surfaces, using point focus for single-point measurements or scanning for multi-point measurements. QVI TTL lasers are compatible with all SmartScope<sup>®</sup> Flash<sup>™</sup> and ZIP measuring systems.

- TTL convenience The TTL laser is coaxial with system optics, allowing use for measurement or as a laser pointer
- Use with other sensors Switch instantaneously between video and laser measurements
- Long working distance Scan surfaces without risk of striking a part or fixture
- Auto tracking The laser dynamically adjusts the Z-axis to track part contours automatically
- Laser lens included –
  A 2.0x laser lens that enhances
  laser and video performance is
  included

Through-the-Lens Laser for Point Focus and Surface Scanning





# **SmartScope® TTL Laser**



### Technical Specifications<sup>1</sup>

Available for	Any OGP <sup>®</sup> SmartScope <sup>®</sup> Flash <sup>™</sup> or ZIP dimensional measurement system	
Required metrology software	QVI <sup>®</sup> ZONE3 <sup>®</sup> , MeasureMind <sup>®</sup> 3D MultiSensor, or Measure-X <sup>®</sup>	
	Standard (with 2.0x Laser Lens)	Optional (with 5.0x Laser Lens)
Working distance	38 mm	19 mm
Measuring range <sup>2</sup>	500 μm	80 µm
Capture range <sup>3</sup>	±3 mm	±400 μm
Triangulation angle	14°	35°
Spot size⁴ (nominal-FWHM)	8x6 μm	3x1.2 µm
<b>Resolution⁵</b>	0.4 µm	0.2 μm

#### Footnotes and Definitions

<sup>1</sup>Specifications are nominal for TTL lasers installed on QVI systems when used in the specified operating environment. <sup>2</sup>Measuring Range tracks within system's Z-axis travel range. <sup>3</sup>Capture Range is surface dependent. <sup>4</sup>Spot size at best focus.

 ${}^{_{5}}\!Using$  high quality specular surface, 10.

Measuring Range - The Z-range over which the performance of the sensor is linear and calibrated. The measuring range lies within the capture range.

**Capture Range** - The Z-range over which there is no uncertainty about which direction the surface lies, but a portion of which may be non-linear and uncalibrated. If the surface is within the capture range, the measuring system will drive the sensor until it is within its measuring range.



### **Safety Considerations**

This system is classified as a Class II laser device by IEC 825 (2001). **Do not stare directly into the laser source.** 



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